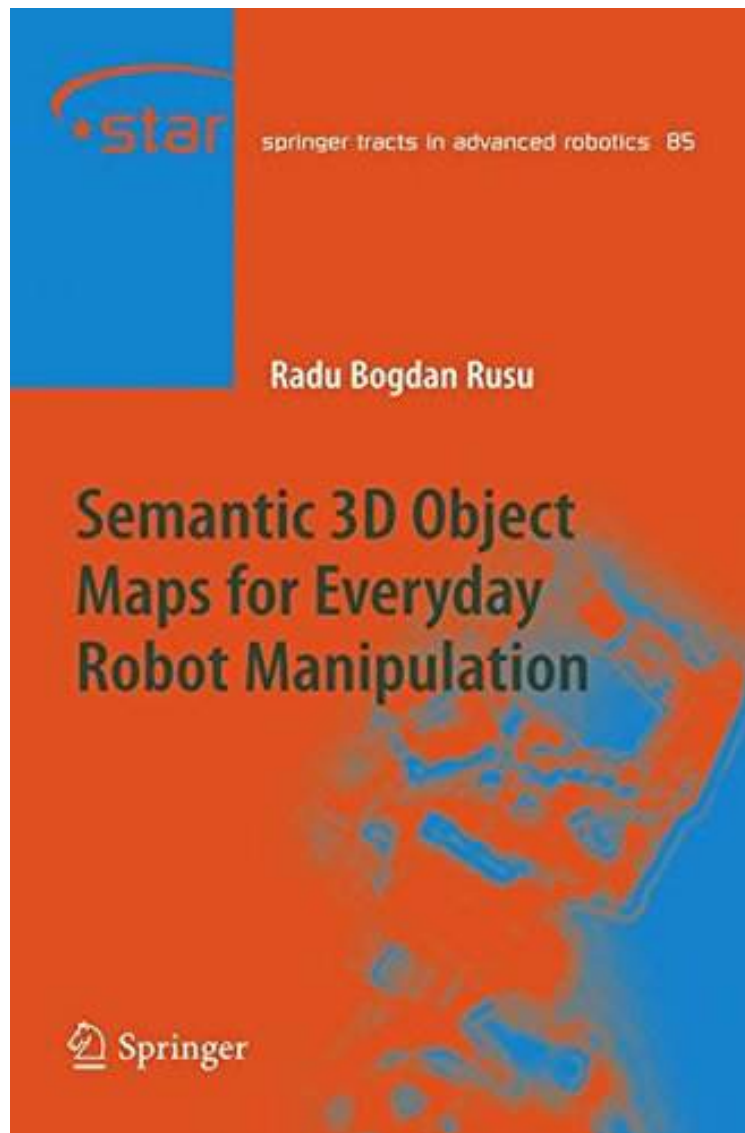


Semantic 3D Object Maps for Everyday Robot Manipulation (Springer Tracts in Advanced Robotics)

# Semantic 3D Object Maps for Everyday Robot Manipulation (Springer Tracts in Advanced Robotics)

*By Radu Bogdan Rusu*



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