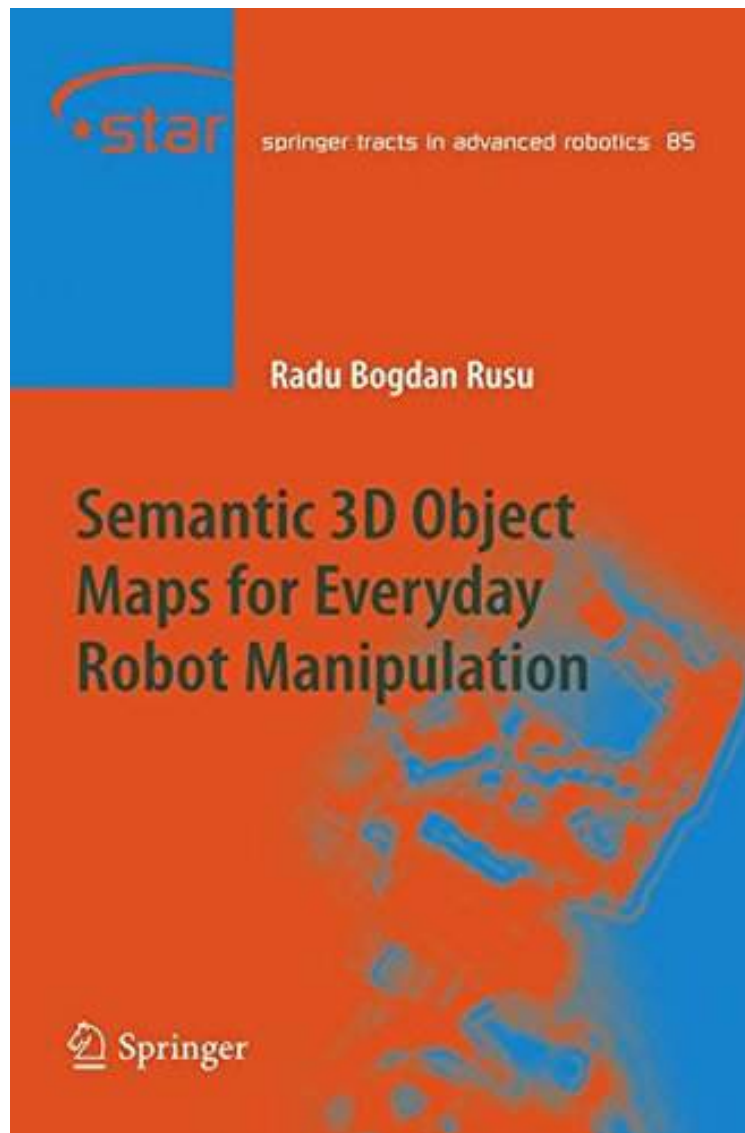


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Semantic 3D Object Maps for Everyday Robot Manipulation (Springer Tracts in Advanced Robotics)

By Radu Bogdan Rusu



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