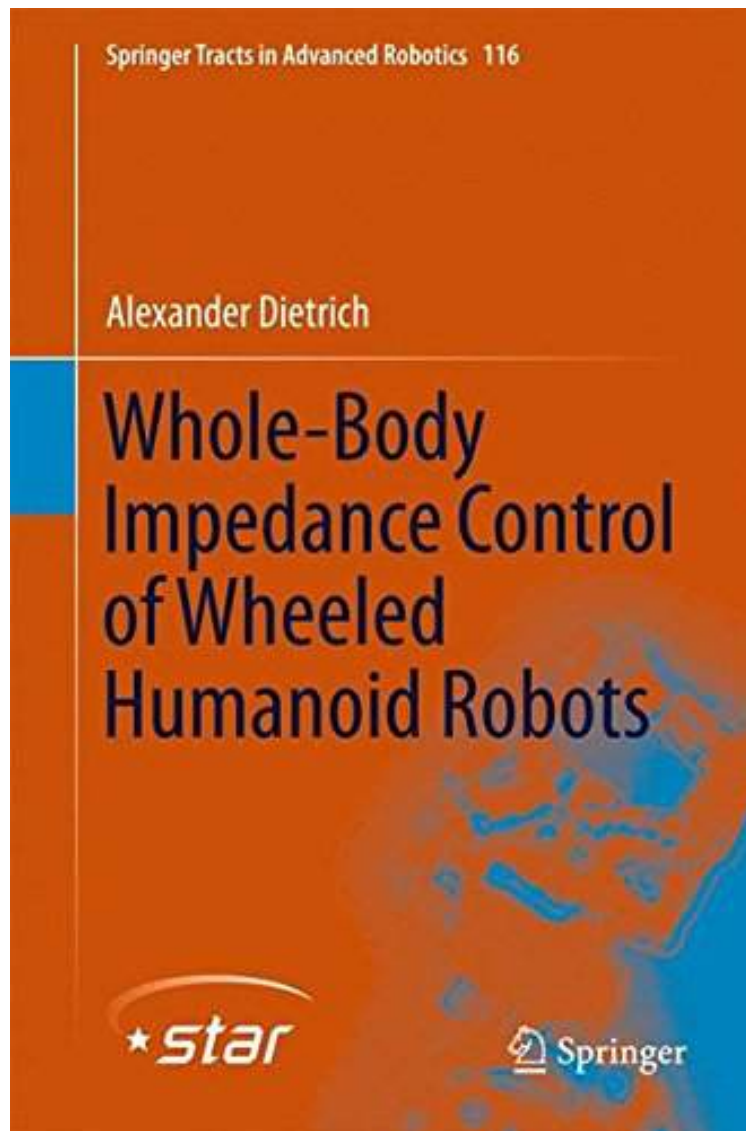


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# Whole-Body Impedance Control of Wheeled Humanoid Robots (Springer Tracts in Advanced Robotics)

*By Alexander Dietrich*



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